

Gujarati Ocr: Compound Character Recognition Using Zernike Moment Feature Extractor

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ABSTRACT

Today most of people are e-reader. Gujarati documents are mostly in hardcopy; very less e-material is available. For converting those hardcopies into editable text form we need digitization. Optical Character Recognition is a technique for converting scanned documents into digitized text. So also for Gujarati language, optical character recognition system is required. For the recognition of printed characters of Indian languages like Gujarati, Marathi and many more; optical character recognition is required. Efforts of many researchers are going on for developing efficient OCR systems for Indian languages, especially for Gujarati, a popular language state Gujarat. There is very less material available for Gujarati script. Devnagari language is the base of Gujarati language. Only difference is shirorekha. Since 1999, efforts are going on for Gujarati character recognition but still that much accuracy cannot be obtained as compared to other Indic languages.

Keywords —Gujarati Character Recognition, Pre-processing, Segmentation, Feature Extraction, OCR

I. INTRODUCTION

Now a day, everything is going in the form of digital. Most of users are becoming e-users then all documents which are going to delivered them should be in digitized format. In recent years, the huge usage of internet had turned people to more usage to electronic documents compared to physical documents. The creation of electronic documents facilitate to easy communication and storage of documents. Thus, developing computer algorithms to identify the characters in the text is the principal task of OCR. Optical character recognition belongs to the family of techniques performing automatic identification.

The overwhelming volume of paper-based data in corporations and offices challenges their ability to manage documents and records. Computers, working faster and more efficiently than human operators, can be used to perform many of the tasks required for efficient document and content management. Computers understand alphanumeric characters as ASCII code typed on a keyboard where each character or letter represents a recognizable code [1].

However, computers cannot distinguish characters and words from scanned images of paper documents. Therefore, where alphanumeric information must be retrieved from scanned images such as commercial or government documents, tax returns, passport applications and .credit card applications, characters must first be converted to their ASCII equivalents before they can be recognized as readable text. Optical character recognition system (OCR) allows us to convert a document into electronic text, which we can edit and search etc. OCR is the machine replication of human reading and has been the subject of intensive research for more than five decades [1].

A. Introduction to Gujarati Script

Gujarati script is derived from Devnagari script. It has very rich set of consonants and vowels. It has 34 consonants as shown in Fig. 1 and 12 vowels as in Table I. By combining consonants and vowels, compound characters are created. Compound characters are also known as conjuncts. Conjuncts are shown in Table II. These conjuncts make Gujarati script more complex compared to other Latin language. Gujarati script is written from left to right. The basic difference between Devnagari script and Gujarati script is absence on shirorekha [2].

ક	ખ	ગ	ઘ	ઙ
ચ	છ	જ	ઝ	ઞ
ટ	ઠ	ડ	ઢ	ણ
ત	થ	દ	ધ	ન
પ	ફ	બ	ભ	મ
ય	ર	લ	વ	
શ	ષ	સ		
હ	ળ	ક્ષ	જ્ઞ	

Fig. 1 Gujarati Consonants

TABLE I
GUJARATI VOWELS

અ	આ	ઇ	ઈ	ઉ	ઊ	એ	ઐ	ઓ	ઔ	અં	અઃ
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TABLE III
EXAMPLE OF GUJARATI CONJUNCTS

વ્ય	ત્ય	જ્ય	ર્ય
બ્હ	ભ્ય	ઝ્હ	ઞ્હ
ધ્	ધ્વ	જ્ઞ	શ્વ

B. Flow of Optical Character Recognition

Fig. 2 shows the flow of character recognition system [1].

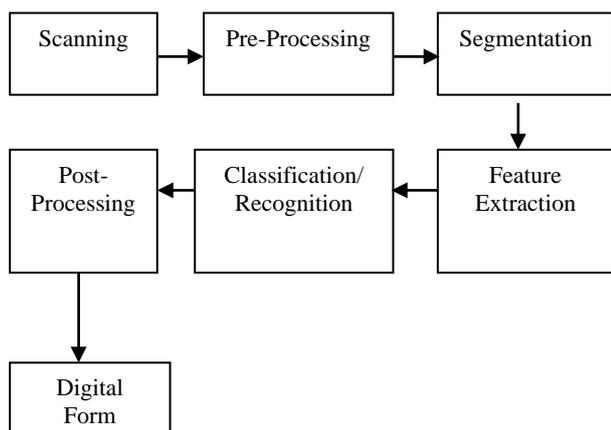


Fig. 2 Flow of OCR

II. PROPOSED APPROACH

A. Pre-Processing

Pre-Processing includes Binarization, Noise removal, Skew detection and correction. We have assumed that our scanned images are skew-free.

1) **Binarization:** Binarization converts the gray scale image into binary image. From the reported work [11], there are mainly two approaches for converting image into binary image. Binarization separates the foreground and background information. This separation of text from background is a prerequisite to subsequent operations such as segmentation.

- Global algorithm
- Local Algorithm

Examples of global algorithm are Otsu’s method, Histogram peaks, and K-mean clustering based method. Examples of local algorithm are Niblack’s method, Sauvola’s method, Bernsen’s Method. The most commonly used method is Otsu’s method. We have used Otsu's method.

2) **Noise removal:** Due to printer, scanner, print quality, age of the document, the documents which are scanned may have noise. So, it is pre-requisite to filter this noise before processing the image. Commonly used approach is to process the image through a low-pass filter and use it for later processing. Median filter is best suitable for salt and pepper kind of noise. Maximum filter is used for removing negative outlier noise. Minimum filter is used for removing dark values in image [12]. We have used median filter for removing noise.

3) **Segmentation:** An image which is passed from the pre-processing phase is ready for the segmentation process. Commonly used segmentation algorithms are Projection profile, Run-length smearing, Hough transforms [15]. Segmentation contains three steps:

- Line Segmentation-Projection and Hough-based methods are suitable for clearly separated lines [15].

Projection-based methods can cope with few overlapping or touching components. Projection-profiles are commonly used for printed document segmentation. The global horizontal projection is used to compute the sum of pixels in each row and construct corresponding histogram. Find the rows which are not contain white pixel using histogram. Based on the peak/valley points of the histogram, individual lines are separated. As shown in Fig-8, each binarized line is separated.

- Word Segmentation- For separate words from segmented line, line is scanned vertically. Number of black pixels in each column is calculated to construct column histogram. Vertical histogram is used for word segmentation [16]. Using the vertical Histogram, find the points from which the word starts and ends. Fig-11 shows the words segmented from Fig-8.

- Character Segmentation- For segmenting characters, vertical histogram of segmented word is created. Using the histogram, find the points from which the character starts and ends [16]. In a word, spaces between characters are the separators between the characters. ㄱ, ㅋ, ㆁ, ㄷ are the major cause for over segmentation resulting into inaccuracy. It is thus necessary to combine the over segmented characters at letter stage to form a single character for recognition as shown in Fig-13. Solution for this problem is as below:

- Do character separation
- Find the width of current character and previous character
- If it’s 3/4th of the previous character width then we merge both the character and it became one as character.

4) **Feature Extraction:** In feature extraction stage each character is represented as a feature vector, which becomes its identity. The major goal of feature extraction is to extract a set of features, which maximizes the recognition rate with the least amount of elements. Feature extraction methods are based on 2 types of features [17]:

- Global or Statistical
- Structural or topological features

5) **Feature Extraction using Zernike Moments:** Zernike moments are a class of orthogonal moments. The orthogonal property of Zernike polynomials enables the contribution of each moment to be unique and independent of information in an image. Fig. 3 shows the complete flow of calculation of Zernike moments [19].

The translation normalization is achieved by moving the image center to the image centroid. The scale normalization is achieved by set the image's 0th order regular moment to a predetermined value. To compute the Zernike moments of a digital image, the range of the image should be mapped to the unit circle first with its origin at the image's center. The pixels falling outside the unit circle are discarded in the computation process. Zernike polynomials take the unit disk $x^2 + y^2 = 1$ as their computation domain [20].

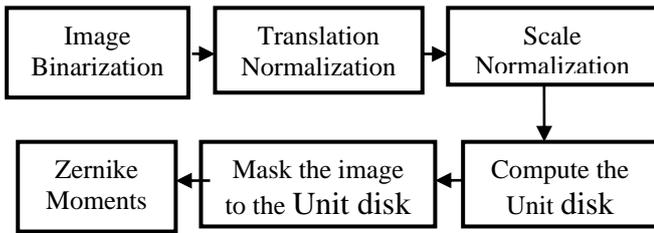


Fig. 3 Block diagram of computing Zernike moments

In my implementation of Zernike moments, I use binary images with spatial resolution of 128×128. All of these binary images are normalized into a unit circle with fixed radius of 64 pixels. Following steps are necessary to extract features of any character image using Zernike moments.

Step 1: First of all converts gray-scale image into the binary numeral image

Step 2: To map over a unit disc image be convert into polar coordinate

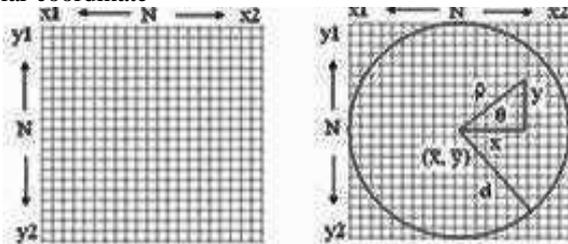


Fig. 4 (a)NxN pixels (b)Unit Circle Mapped image bitmap onto NxN pixel size image

In the above Fig. 4(a) the center of the image and disk is same. Where x_1x_2 are X-axis dimensions and y_1y_2 is Y-axis dimensions of the pixel rectangle. (\bar{x}, \bar{y}) is the center of the unit disk, ρ is polar value and θ is polar angle. Now the image is mapped into polar co-ordinates and onto unit circle as:

Compute the distance d in Fig. 4(b) above as

$$d = \sqrt{(x_2 - \bar{x})^2 \frac{1}{2} + (y_2 - \bar{y})^2 \frac{1}{2}} \quad (1)$$

Compute the distance vector ρ and angle θ for any (x, y) pixel in $f(x, y)$ polar coordinates as

$$\rho = \sqrt{(x - \bar{x})^2 + (y - \bar{y})^2} / d \quad (2)$$

$$\theta = \tan^{-1} \left[\frac{x - \bar{x}}{y - \bar{y}} \right] \quad (3)$$

This step maps pixel coordinate (x_1, x_2) to $(-1, +1)$ and (y_1, y_2) to $(-1, +1)$ in polar. In this way almost all the pixels in image bound box as above are inside unit circle except some foreground pixels.

Step 3: Zernike introduced a set of complex polynomials $\{V_{nm}(x, y)\}$ which form a complete orthogonal set over the unit disk of $x^2 + y^2 \leq 1$ in polar coordinates. The form of the polynomials is:

$$V_{nm}(x, y) = V_{nm}(\rho, \theta) = R_{nm}(\rho) e^{jm\theta} \quad (4)$$

Where $j = \sqrt{-1}$, $\theta = \tan^{-1} y/x$, ρ is the length of the vector from the origin to the pixel (x, y) , θ is the angle between the vector ρ and x axis in counter clockwise direction. $R_{nm}(\rho)$ is Radial polynomial defined as [20]:

$$R_{nm}(\rho) = \sum_{s=0}^{(n-|m|)/2} (-1)^s \frac{(n-s)!}{s! \left(\frac{n+|m|}{2}-s\right)! \left(\frac{n-|m|}{2}-s\right)!} \rho^{n-2s} \quad (5)$$

Where $n \geq 0$, $|m| \leq n$, $n-|m| = \text{even}$. When the image is mapped onto unit disc, take desired value of order of moment, i.e. n and compute real and imaginary parts of the Zernike moment using Radial polynomials.

Step 4: Then compute Zernike moment of order n and repetition m for function $f(x, y)$ is defined as:

$$A_{nm} = \frac{n+1}{\pi} \sum_x \sum_y f(x, y) V_{nm}^*(x, y), x^2 + y^2 \leq 1 \quad (6)$$

Where $n \geq 0$, $|m| \leq n$ and $*$ is the complex conjugate operator [21].

6) Classification using K-NN classifier: The classification stage is the decision making part of a recognition system and it uses the features extracted in the feature extraction stage. Classification stage in an OCR process assigns labels to character images based on the features extracted and the relationships among the features. K-NN is an instance based classification algorithm. To classify a new character, the system finds the k -nearest neighbors among the training datasets, and uses the categories of the k -nearest neighbors to weight the category candidates. Euclidean distance is considered as distance function between train data and test data. Euclidean distance between two n dimensional vectors a and b can be calculated as [21]:

$$\Delta_{\text{Euclidean}}(x, y) = \sqrt{\sum_{i=1}^n (a_i - b_i)^2} \quad (7)$$

III. EXPERIMENTAL RESULTS

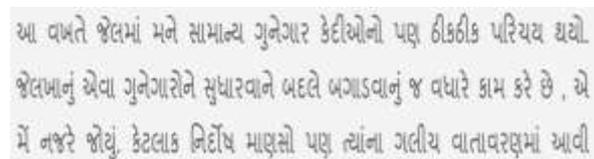


Fig. 5 Original Image

આ વખતે જેલમાં મને સામાન્ય ગુનેગાર કેદીઓનો પણ ઠીકઠીક પરિચય થયો. જેલખાનું એવા ગુનેગારોને સુધારવાને બદલે બગાડવાનું જ વધારે કામ કરે છે, એ મેં નજરે જોયું. કેટલાક નિર્દોષ માણસો પણ ત્યાંના ગલીય વાતાવરણમાં આવી

Fig. 6 Gray-Scale Image

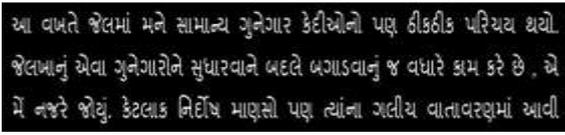


Fig. 7 Binary Image

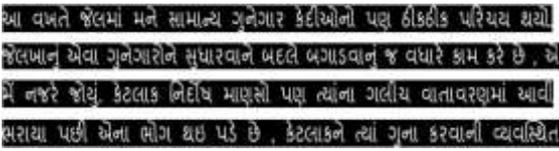


Fig. 8 Segmented Lines

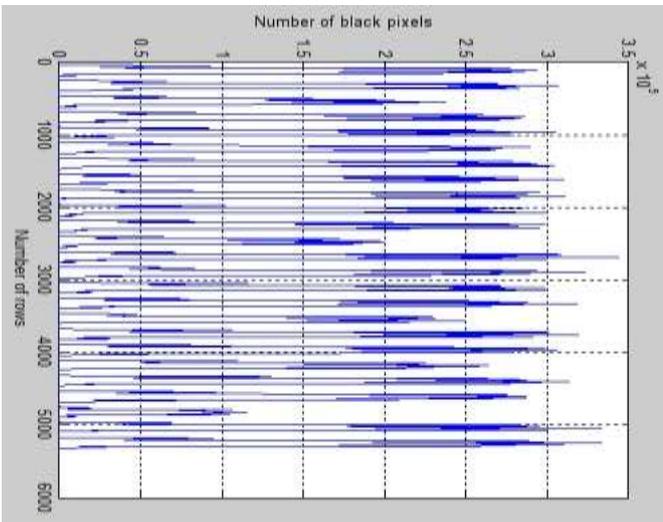


Fig. 9 Horizontal histogram for line segmentation

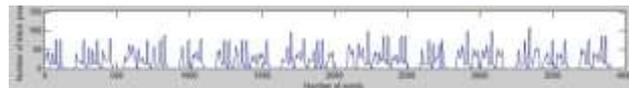


Fig. 10 Vertical histogram for word segmentation



Fig. 11 Segmented Words

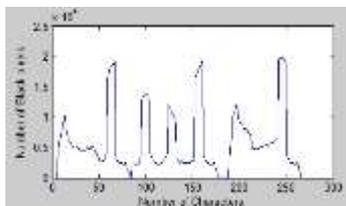


Fig. 12 Vertical histogram for character segmentation



Fig. 13 Segmented Characters

TABLE III
RESULT OF LINE SEGMENTATION

Name	Total No. of Lines	Correctly segment-ed Lines	Incorrectly Segmen-ted Lines	Accu-racy (%)
gocr-1	25	25	0	100%
gocr-2	24	24	0	100%
gocr-3	25	25	0	100%
gocr-4	25	25	0	100%
gocr-5	25	25	0	100%
gocr-6	25	25	0	100%
gocr-7	25	25	0	100%
gocr-8	24	24	0	100%
gocr-9	24	24	0	100%
gocr-10	25	25	0	100%
			Average Accuracy	100%

TABLE IV
RESULT OF CHARACTER SEGMENTATION

Names	Total No. of chara-cters	CorrectS egment-ed Characte-rs	Incorrect Segmente-d Characte-rs	Accu-Racy (%)
gocr-1	758	694	64	91.55
gocr-2	709	631	78	88.99
gocr-3	720	645	75	89.58
gocr-4	727	659	68	90.64
gocr-5	648	602	46	92.90
gocr-6	766	694	72	90.60
gocr-7	751	686	65	91.34
gocr-8	761	698	63	91.72
gocr-9	715	655	60	91.60
gocr-10	751	674	77	89.74
			Average Accuracy	90.866

TABLE V
CONJUNCTS USED FOR CLASSIFICATION

ચ	હ	ધ	ઝ	ઞ	ત	થ	કસ	કટ	કત
લ	લ્ય	મ	ન્	ન્મ	ન્ન	ણ	ન્ય	પ્ર	ય
ડ	ર્ગ	ર્મ	ર્ણ	ર્શ	ર્ષ	ર્ટ	ર્ત	ર્થ	ર્વ
ર્ય	શ્ર	શ્ર	ષ	શ્વ	સ્મ	સ્પ	સ્ત	સ્થ	સ્વ
થ્ય	ત્ય	ત્ર	ત્સ	ત્ય	વ્ર	વ્ય	ક્ષ	દ્ર	ન્શ



Fig. 14 Original image

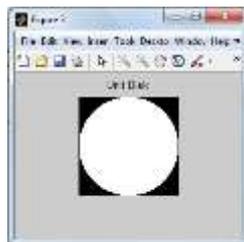


Fig. 15 Unit disk



Fig. 18 Character in editable text



Fig. 16 Mapping of image Reconstruction On Unit Disk



Fig. 17 of Character

IV. CONCLUSIONS

From this experimental results, I have concluded that feature extraction of Gujarati language can be done using Zernike moments.

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TABLE VI
UNICODE FOR CONSONANTS

x=	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
U+ 0A8x		ઁ	ઃ	ઃ		અ	બ	ઇ	ઇ	ઉ	ઝ	ઞ	ટ	ઠ	ડ	ઢ
U+ 0A9x	એ	ઐ	ઓ	ઔ	ક	ખ	ગ	ઘ	ઙ	ચ	છ	જ	ઝ	ઞ	ટ	ઠ
U+ 0AAx	ઠ	ડ	ઢ	ણ	ત	થ	દ	ધ	ન		પ	ફ	બ	ભ	મ	ય
U+ 0ABx	ર		લ	ળ		વ	શ	ષ	સ	હ			્	્	્	્
U+ 0ACx	ી	ૃ	ૄ	ૅ	૆	ે		ૈ	ૉ		ૌ	્	્	્	્	્
U+ 0ADx	ં															
U+ 0AEx	ઋ	ૠ	ૡ	ૢ		ૣ	૤	૥	૦	૧	૨	૩	૪	૫	૬	૭
U+ 0AFx	૮	૯														

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